

Automatyka i robotyka - studia niestacjonarne I stopnia (WI)
rok IV, semestr 7

| | | 1 9 paź | 2 16 paź | 3 23 paź | 4 6 lis | 5 20 lis | 6 27 lis | 7 4 gru | 8 11 gru | 9 18 gru | 10 8 sty | 11 15 sty | 12 22 sty |
|----------------|---|-----------------------|-------------------|----------------------|-----------------------|-----------------------|-----------------------|----------------------|-----------------------|-----------------------|-------------|-----------------------|--------------|
| | | A-1 L-1 | A-1 L-1 | A-1 L-1 | A-1 L-1 | A-1 L-1 | A-1 L-1 | A-1 L-1 | A-1 L-1 | A-1 L-1 | A-1 L-1 | A-1 L-1 | A-1 L-1 |
| 08:00 09:30 | 1 | PO 9: PSM 325 | PO 11: PSO 325 | PO 11: PSO -L 112 | PO 11: PSO 325 | PO 11: PSO 325 | PO 8: UNwR 325 | PO 8: UNwR -L 427 | PO 8: UNwR 325 | | | PO 8: UNwR 325 | |
| 09:45 11:15 | 2 | PO 9: PSM 325 | PO 11: PSO 325 | PO 11: PSO -L 112 | PO 11: PSO 325 | PO 11: PSO 325 | PO 8: UNwR 325 | PO 8: UNwR -L 427 | PO 8: UNwR 325 | PO 11: PSO 325 | | PO 6: SCADA 325 | |
| 11:30 13:00 | 3 | PO 7: SysRA 325 | SI /JJ 325 | SI /JJ 311 | PO 7: SysRA 325 | PO 6: SCADA 325 | PO 7: SysRA 325 | PO 11: PSO 325 | PO 7: SysRA 325 | PO 7: SysRA -L 427 | | PO 6: SCADA -L 427 | |
| 13:30 15:00 | 4 | PO 7: SysRA 325 | SI /JJ 325 | SI /JJ 311 | PO 7: SysRA 325 | PO 6: SCADA 325 | PO 7: SysRA 325 | PO 11: PSO 325 | PO 7: SysRA 325 | PO 7: SysRA -L 427 | | PO 7: SysRA -L 427 | |
| 15:10 16:40 | 5 | PO 7: SysRA -L 427 | PO 10: PE 325 | PO 10: PE 325 | PO 7: SysRA -L 427 | PO 6: SCADA -L 427 | PO 7: SysRA -L 427 | PO 10: PE 325 | PO 7: SysRA -L 427 | PO 8: UNwR 325 | | PO 7: SysRA -L 427 | |
| 16:50 18:20 | 6 | PO 7: SysRA -L 427 | PO 10: PE 325 | PO 10: PE 325 | PO 7: SysRA -L 427 | PO 6: SCADA -L 427 | PO 7: SysRA -L 427 | PO 10: PE 325 | PO 7: SysRA -L 427 | PO 8: UNwR 325 | | | |
| 18:30 20:00 | 7 | | | | | | | | | | | | |

| | | 10 paź | 17 paź | 24 paź | 7 lis | 21 lis | 28 lis | 5 gru | 12 gru | 19 gru | 9 sty | 16 sty | 23 sty |
|----------------|---|--------|-----------------------|----------------------|----------------|----------------------|------------------|-----------------------|----------------------|-----------------------|-------|----------------------|--------|
| 08:00 09:30 | 1 | | PO 6: SCADA 216 | PO 9: PSM 308 | SI /AM 312 | PO 11: PSO -L 112 | SI /AM 216 | PO 11: PSO -L 112 | PO 8: UNwR -L 427 | SI -L 45 cW | | PO 8: UNwR -L 427 | |
| 09:45 11:15 | 2 | | PO 6: SCADA 216 | PO 9: PSM 308 | SI /AM 312 | PO 11: PSO -L 112 | SI /AM 216 | PO 11: PSO -L 112 | PO 8: UNwR -L 427 | SI -L 45 cW | | PO 11: PSO -L 112 | |
| 11:30 13:00 | 3 | | PO 6: SCADA -L 427 | PO 8: UNwR 325 | SI -L 45 cW | PO 8: UNwR -L 427 | SI -L 45 cW | PO 6: SCADA 325 | PO 9: PSM 325 | PO 6: SCADA 325 | | | |
| 13:30 15:00 | 4 | | PO 6: SCADA -L 427 | PO 8: UNwR 325 | SI -L 45 cW | PO 8: UNwR -L 427 | SI -L 45 cW | PO 6: SCADA 325 | PO 9: PSM 325 | PO 6: SCADA 325 | | | |
| 15:10 16:40 | 5 | | | PO 8: UNwR -L 427 | | | PO 9: PSM 325 | PO 6: SCADA -L 427 | PO 11: PSO -L 112 | PO 6: SCADA -L 427 | | | |
| 16:50 18:20 | 6 | | | PO 8: UNwR -L 427 | | | PO 9: PSM 325 | PO 6: SCADA -L 427 | PO 11: PSO -L 112 | PO 6: SCADA -L 427 | | | |
| 18:30 20:00 | 7 | | | | | | | | | | | | |

| | W | C | L | P |
|---|----|----|----|--|
| PO 6: Systemy SCADA | 18 | | 18 | dr inż. P. Sauer |
| PO 7: Systemy rozproszone automatyki | E | 16 | 24 | dr inż. J. Majchrzak |
| PO 8: Układy napędowe w robotyce | E | 18 | 18 | dr inż. P. Sauer (W), mgr inż. T. Jedwabny |
| Sztuczna inteligencja i systemy wspomaganie decyzji | | 16 | 12 | prof. dr hab. Inż. J. Józefowska (W), A. Michalski (W+L) |
| PO 9: Projektowanie systemów mechatronicznych | | 16 | | dr inż. B. Krysiak |
| PO 10: Podstawy ekonomii | | 12 | | dr M. Rembiasz |
| PO 11: Podstawy sterowania optymalnego | E | 18 | 18 | dr hab. inż. S. Stępień, prof. PP; mgr inż. K. Hałas |